

$\theta \ll 1$  של התנה (1).

$$T = mg$$

התנאי של  $\theta \ll 1$  מוביל לביטוי  $\theta = \frac{x_2 - x_1}{L}$

התנאי של  $\theta \ll 1$  מוביל לביטוי  $\theta = \frac{x_2 - x_1}{L}$

$$\vec{r}_1 = x_1 \hat{x}$$

$$\vec{r}_2 = (x_1 + L \sin \theta) \hat{x} \approx (x_1 + L \theta) \hat{x}$$

$$\dot{\vec{r}}_1 = \dot{x}_1$$

$$\dot{\vec{r}}_2 = \dot{x}_1 + L \dot{\theta} = \dot{x}_1 + \dot{x}_2 - \dot{x}_1 = \dot{x}_2$$

$$\theta = \frac{x_2 - x_1}{L} \quad (1c)$$

$$\Rightarrow \begin{cases} M \ddot{x}_1 = -kx_1 + mg\theta = -kx_1 + mg \frac{x_2 - x_1}{L} \\ m \ddot{x}_2 = -mg\theta = -mg \frac{x_2 - x_1}{L} \end{cases}$$

$$\begin{cases} m \ddot{x}_1 = -kx_1 + m \frac{g}{L} (x_2 - x_1) \\ m \ddot{x}_2 = -mg \frac{1}{L} (x_2 - x_1) \end{cases}$$

$$M = m \quad (2)$$

$$\begin{cases} \ddot{x}_1 = -\omega_s^2 x_1 + \omega_p^2 x_2 - \omega_p^2 x_1 \\ \ddot{x}_2 = -\omega_p^2 x_2 + \omega_p^2 x_1 \end{cases}$$

$$\omega_p^2 = \frac{g}{L}$$

$$\omega_s^2 = \frac{k}{m}$$

$$\begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} + \underbrace{\begin{pmatrix} \omega_s^2 + \omega_p^2 & -\omega_p^2 \\ -\omega_p^2 & \omega_p^2 \end{pmatrix}}_A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$$

$$\begin{vmatrix} \omega_s^2 + \omega_p^2 - \omega^2 & -\omega_p^2 \\ -\omega_p^2 & \omega_p^2 - \omega^2 \end{vmatrix} = 0 = (\omega_s^2 + \omega_p^2 - \omega^2)(\omega_p^2 - \omega^2) - \omega_p^4 =$$

$$= \omega_s^2 \omega_p^2 - \omega_s^2 \omega^2 + \omega_p^4 - \omega_p^2 \omega^2 - \omega_p^2 \omega^2 + \omega^4 - \omega_p^4 = 0$$

$$\omega^4 - \omega^2 (2\omega_p^2 + \omega_s^2) + \omega_s^2 \omega_p^2 = 0$$

$$\omega_{1,2}^2 = \frac{2\omega_p^2 + \omega_s^2 \pm \sqrt{4\omega_p^4 + 4\omega_p^2\omega_s^2 + \omega_s^4 - 4\omega_s^2\omega_p^2}}{2} =$$

$$= \frac{1}{2} (2\omega_p^2 + \omega_s^2 \pm \sqrt{4\omega_p^4 + \omega_s^4})$$

$$\omega_1^2 = \omega_p^2 + \frac{1}{2}\omega_s^2 + \frac{1}{2}\sqrt{4\omega_p^4 + \omega_s^4}$$

$$\begin{pmatrix} \frac{1}{2}\omega_s^2 - \frac{1}{2}\sqrt{4\omega_p^4 + \omega_s^4} & -\omega_p^2 \\ -\omega_p^2 & -\frac{1}{2}\omega_s^2 - \frac{1}{2}\sqrt{4\omega_p^4 + \omega_s^4} \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 0$$

$$\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} \frac{-\frac{1}{2}\omega_s^2 - \frac{1}{2}\sqrt{4\omega_p^4 + \omega_s^4}}{\omega_p^2} \\ 1 \end{pmatrix}$$

$$\omega_2^2 = \omega_p^2 + \frac{1}{2}\omega_s^2 - \frac{1}{2}\sqrt{4\omega_p^4 + \omega_s^4}$$

$$\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} \frac{-\frac{1}{2}\omega_s^2 + \frac{1}{2}\sqrt{4\omega_p^4 + \omega_s^4}}{\omega_p^2} \\ 1 \end{pmatrix}$$

$$\omega_1^2 \approx 2\omega_p^2$$

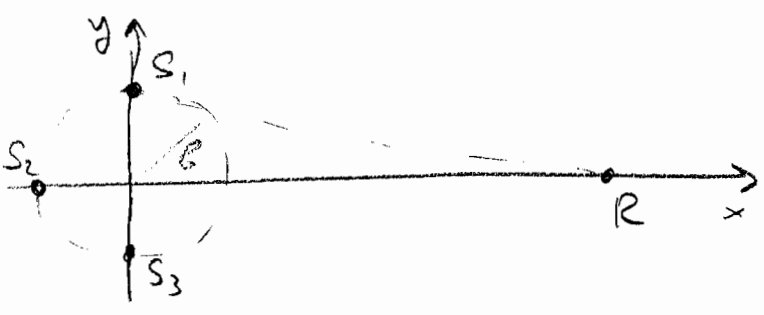
$$\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\omega_2^2 = 0$$

$$\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\omega_p \gg \omega_s$$





$$\vec{E}_i = A e^{i(\omega t - \vec{k} \cdot \vec{r})}$$

$$I_0 = \langle \vec{E} \cdot \vec{E}^* \rangle = A^2$$

$$k = \frac{2\pi}{\lambda}$$

$$E_R = A e^{i\omega t} (2e^{-ik\sqrt{R^2+b^2}} + e^{-ik(R+b)}) =$$

$$= A e^{i\omega t} (2e^{-ikR\sqrt{1+(\frac{b}{R})^2}} + e^{-ik(R+b)}) =$$

$$= A e^{i\omega t} (2e^{-ikR} e^{-ik\frac{1}{2}\frac{b^2}{R}} + e^{-ikR} e^{-ikb}) =$$

$$= A e^{i(\omega t - kR)} (2e^{-\frac{1}{2}ik\frac{b^2}{R}} + e^{-ikb})$$

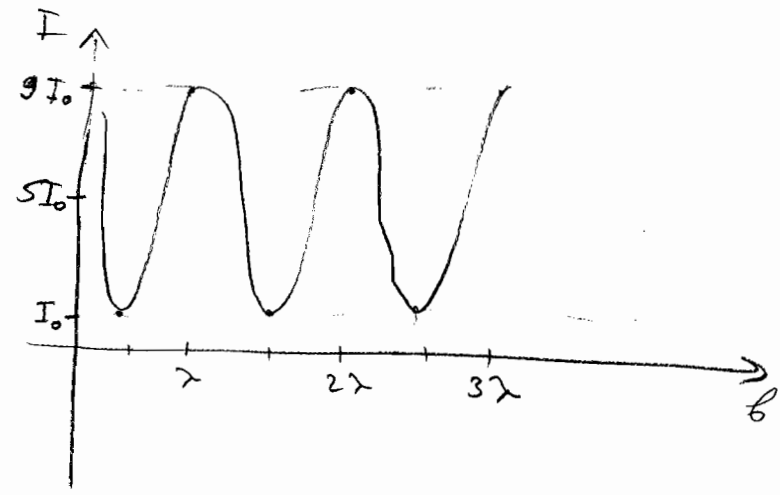
$$\vec{E}_R \cdot \vec{E}_R^* = A^2 (2e^{-\frac{1}{2}ik\frac{b^2}{R}} + e^{-ikb}) (2e^{\frac{1}{2}ik\frac{b^2}{R}} + e^{ikb}) =$$

$$= A^2 (4 + 1 + 2e^{ikb(1 - \frac{1}{2}\frac{b}{R})} + 2e^{-ikb(1 - \frac{1}{2}\frac{b}{R})}) =$$

$$= A^2 (5 + 4 \cos [kb(1 - \frac{1}{2}\frac{b}{R})])$$

$$I = I_0 (5 + 4 \cos [kb(1 - \frac{1}{2}\frac{b}{R})]) \approx \quad b \ll R$$

$$\approx I_0 (5 + 4 \cos kb) = I_0 (5 + 4 \cos \frac{2\pi}{\lambda} b)$$



max:  $b = n\lambda, \quad n = 1, 2, \dots$

min:  $b = \frac{1}{2}n\lambda, \quad n = 1, 2, \dots$

② בתוך פיסת המראה הנ"ל, נהיה כוונת האור  $\frac{c}{n}$  וכן  $\mu$ .

$$k'b = \frac{\omega}{v} b = \frac{\omega}{c} n b = k n b$$

הכנסו הכאן ה'א'

$$E_R = A e^{i\omega t} (2e^{-ik\sqrt{R^2+b^2}} + e^{-ikR-ik'b})$$

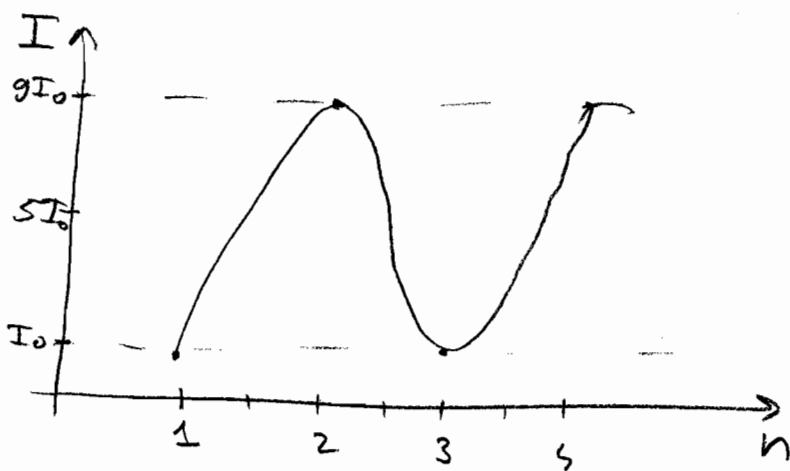
$$\approx A e^{i(\omega t - kR)} (2 + e^{-iknb})$$

$$\vec{E}_R \cdot \vec{E}_R^* = A^2 (4 + 1 + 4 \cos knb)$$

$$I = I_0 (5 + 4 \cos knb) = \leftarrow b = \frac{\lambda}{2}$$

$$= I_0 \left( 5 + 4 \cos \frac{2\pi}{\lambda} n \frac{\lambda}{2} \right) =$$

$$= I_0 (5 + 4 \cos \pi n)$$



max:  $n = 2, 4, \dots$

min:  $n = 1, 3, \dots$

## Membrane

Write the mode as

$$\Psi(x, y, t) = f(x, y) \cos(\omega t + \phi) \quad (1)$$

and write  $f(x, y)$  as a Fourier expansion

$$f(x, y) = \sum_{nm} A_{nm} \sin(k_n x + \phi_n) \sin(k_m y + \phi_m) \quad (2)$$

Apply the boundary conditions (without the fixed point)

$$f(0, y) = f(L, y) = f(x, 0) = 0 \quad (3)$$

$$\frac{\partial f}{\partial y} \Big|_{y=L} = 0 \quad (4)$$

This gives

$$k_n = \frac{\pi n}{L} \quad (5)$$

$$k_m = \frac{\pi m - \pi/2}{L} \quad (6)$$

$$\phi_n = \phi_m = 0 \quad (7)$$

so that

$$f(x, y) = \sum_{nm} A_{nm} \sin\left(\frac{\pi n}{L} x\right) \sin\left(\frac{\pi m - \pi/2}{L} y\right) \quad (8)$$

Substitution into the wave equation gives

$$\omega^2 = v^2 \left[ \left(\frac{\pi n}{L}\right)^2 + \left(\frac{\pi m - \pi/2}{L}\right)^2 \right] \quad (9)$$

A mode of frequency  $\omega$  thus involves a sum over pairs  $n$  and  $m$  that satisfy Eq. (9)

Add the fixed point  $(x_0, y_0) = (L/2, L)$

$$f(x_0, y_0) = - \sum_{nm} A_{nm} \sin\left(\frac{\pi n}{2}\right) \cos(\pi m) = 0 \quad (10)$$

There are two families of solutions.

The first one is for *even*  $n$ 's. For even  $n$  Eq.(10) is satisfied for arbitrary  $m$ , and the mode is

$$\Psi_{nm}(x, y, t) = A_{nm} \sin\left(\frac{\pi n}{L} x\right) \sin\left(\frac{\pi m - \pi/2}{L} y\right) \cos(\omega t + \phi) \quad (11)$$

The second family is for *odd*  $n$ 's. In this case the product of the sines is either  $+1$  or  $-1$ , so this family will consist of pairs, such that one is  $+1$  and the other one is  $-1$ . Let us take odd  $n_1, n_2$  and arbitrary integers  $m_1, m_2$ , and derive the condition for satisfying Eq.(10):

$$A_{n_1 m_1} \sin\left(\frac{\pi n_1}{2}\right) \cos(\pi m_1) + A_{n_2 m_2} \sin\left(\frac{\pi n_2}{2}\right) \cos(\pi m_2) = 0 \quad (12)$$

which gives for odd  $n_1, n_2$

$$\frac{A_{n_1 m_1}}{A_{n_2 m_2}} = - \frac{\sin\left(\frac{\pi n_2}{2}\right) \cos(\pi m_2)}{\sin\left(\frac{\pi n_1}{2}\right) \cos(\pi m_1)} = -(-1)^{n_2/2 - n_1/2 + m_2 - m_1} \quad (13)$$

Then the mode is

$$\Psi_{n_1 m_1 n_2 m_2}(x, y, t) = A_{n_2 m_2} \left[ -(-1)^{n_2/2 - n_1/2 + m_2 - m_1} \sin\left(\frac{\pi n_1}{L}x\right) \sin\left(\frac{\pi m_1 - \pi/2}{L}y\right) + \sin\left(\frac{\pi n_2}{L}x\right) \sin\left(\frac{\pi m_2 - \pi/2}{L}y\right) \right] \cos(\omega t + \phi) \quad (14)$$

The possible values of  $n_1, n_2, m_1, m_2$  follow from the condition (9). In order to know what the possible values of  $n_1, n_2, m_1, m_2$  are, substitute the mode into the wave equation, compare coefficients and obtain:

$$n_1^2 - n_2^2 + (m_1 - 1/2)^2 - (m_2 - 1/2)^2 = 0 \quad (15)$$

So, for example, if  $n_1 = n_2$ , then  $(m_1 - 1/2)^2 = (m_2 - 1/2)^2$ ; another example  $(n_1, n_2, m_1, m_2) = (1, 5, 6, 3)$ .

In order to find the general solution, one can write an odd  $n$  as  $n = 2n' - 1$  and get

$$4(n'_1 + n'_2 - 1)(n'_1 - n'_2) - (m_1 + m_2 - 1)(m_1 - m_2) = 0 \quad (16)$$

$$4N_1 N_2 - M_1 M_2 = 0 \quad (17)$$

where the last equation is for new redefined integers  $N_1 = n'_1 + n'_2 - 1, N_2 = n'_1 - n'_2, M_1 = m_1 + m_2 - 1, M_2 = m_1 - m_2$ . So for a given  $N_1, N_2, M_1$ , there will be a solution for  $M_2$  if  $4N_1 N_2 / M_1$  is an integer.



4

$$\Psi(L, t) = C \cos \omega_1 t \cos \omega_2 t$$

$$\Psi(x) = \sum_n (A_n \cos k'_n x + B_n \sin k'_n x) \cos(\omega'_n t + \varphi_n) \quad \omega = vk$$

$$\begin{cases} x=0: T \frac{\partial \Psi}{\partial x} \Big|_{x=0} = m \frac{\partial^2 \Psi}{\partial t^2} + K \Psi(0) \\ x=L: \Psi(L, t) = C \cos \omega_1 t \cos \omega_2 t = \frac{1}{2} C (\cos(\omega_1 - \omega_2)t + \cos(\omega_1 + \omega_2)t) \end{cases}$$

$$\begin{aligned} \Psi(L, t) &= \sum_n (A_n \cos k'_n L + B_n \sin k'_n L) \cos(\omega'_n t + \varphi_n) = \\ &= \frac{C}{2} \cos(\omega_1 - \omega_2)t + \frac{C}{2} \cos(\omega_1 + \omega_2)t \end{aligned}$$

$$\varphi_n = 0$$

בנוסף, אנו יודעים ש- $\omega = vk$

$$\begin{aligned} A_1 \cos k'_1 L + B_1 \sin k'_1 L &= \frac{C}{2} & \omega'_1 &= \omega_1 - \omega_2 \\ A_2 \cos k'_2 L + B_2 \sin k'_2 L &= \frac{C}{2} & \omega'_2 &= \omega_1 + \omega_2 \end{aligned} \quad (*)$$

$$\Rightarrow \Psi(x, t) = (A_1 \cos k'_1 x + B_1 \sin k'_1 x) \cos(\omega'_1 t) + (A_2 \cos k'_2 x + B_2 \sin k'_2 x) \cos(\omega'_2 t)$$

$$\frac{\partial \Psi}{\partial x} \Big|_{x=0} = B_1 k'_1 \cos(\omega'_1 t) + B_2 k'_2 \cos(\omega'_2 t)$$

$$\frac{\partial^2 \Psi}{\partial t^2} \Big|_{x=0} = -\omega_1'^2 A_1 \cos \omega_1' t - \omega_2'^2 A_2 \cos \omega_2' t$$

$$\begin{aligned} \Rightarrow T B_1 k'_1 \cos \omega_1' t + T B_2 k'_2 \cos \omega_2' t &= \\ = -m \omega_1'^2 A_1 \cos \omega_1' t - m \omega_2'^2 A_2 \cos \omega_2' t + \\ + K A_1 \cos \omega_1' t + K A_2 \cos \omega_2' t \end{aligned}$$

השוונו נכון לכל  $t$  ונשווה את המקדמים של קוסינוסים זהים

$$T B_1 k_1' = -m \omega_1'^2 A_1 + K A_1$$

$$\omega_1' = v k_1' \quad v = \sqrt{\frac{T}{\rho}}$$

$$\Rightarrow \begin{cases} T B_1 k_1' = A_1 (K - m v^2 k_1'^2) \\ T B_2 k_2' = A_2 (K - m v^2 k_2'^2) \end{cases}$$

$$\begin{cases} A_1 \cos k_1' L + B_1 \sin k_2' L = \frac{C}{2} \\ A_2 \cos k_2' L + B_2 \sin k_2' L = \frac{C}{2} \end{cases} \quad (*) \text{ קשר}$$

$$\begin{cases} A_1 \cos k_1' L + B_1 \sin k_2' L = \frac{C}{2} \\ A_2 \cos k_2' L + B_2 \sin k_2' L = \frac{C}{2} \end{cases}$$

(\*) קשר

$A_{1,2}, B_{1,2}$  קשרים בין  $\omega_1, \omega_2$  ל- $\omega_1', \omega_2'$  (קשרים בין  $k_1, k_2$  ל- $k_1', k_2'$ )  
 $(\omega_1' = \omega_1 - \omega_2, \omega_2' = \omega_1 + \omega_2)$  קשרים בין  $k_1, k_2$  ל- $k_1', k_2'$

$$B_1 = -A_1 \frac{m v^2 k_1'^2 - K}{T k_1'}$$

$$A_1 \left( \cos k_1' L - \frac{m v^2 k_1'^2 - K}{T k_1'} \sin k_2' L \right) = \frac{C}{2}$$

$$A_1 = \frac{C/2}{\cos k_1' L - \frac{m v^2 k_1'^2 - K}{T k_1'} \sin k_2' L}$$

$$B_1 = \dots$$

הקשרים בין  $A_1, B_1$  ל- $A_2, B_2$  הם  $A_1, B_1$  הם הקשרים בין  $A_2, B_2$  ל- $A_1, B_1$

$$y(x,t) = \sum_{i=1}^2 (A_i \cos k_i' x + B_i \sin k_i' x) \cos(\omega_i' t) \quad \text{: Load}$$

$$\omega_1' = \omega_1 - \omega_2$$

$$\omega = v k$$

$$\omega_2' = \omega_1 + \omega_2$$



5

התנחת בזה: תראה ששליש קלאסי של אנרגיה סביב  
הכדור והתנע הזוויתי מקוונט.

כיוון שיש להתלבט בשאלה אחת הכדור M וחסר האלקטרון m,  
נציג מסה מצומצמת  $\mu = \frac{mM}{m+M}$  ונרחיב למסכת "זרום  
זה המכנס נ"ח.

$$\begin{cases} \frac{kqZq}{r^2} = \frac{\mu v^2}{r} & \text{תוקטן} \\ L = nh & \text{התנחת בזה} \end{cases}$$

|q| - מסת האלקטרון  
Z|q| - מסת הכדור

$$L = \mu v r = nh$$

$$\mu v^2 = \frac{kZq^2}{r} \Rightarrow v^2 = \frac{kZq^2}{\mu r}$$

$$\mu \frac{k^{1/2} Z^{1/2} q}{\mu^{1/2} r^{1/2}} r = nh$$

$$\mu^{1/2} k^{1/2} Z^{1/2} q r^{1/2} = nh \Rightarrow \frac{1}{r} = \frac{\mu k Z q^2}{n^2 h^2}$$

$$E_n = \frac{1}{2} \mu v^2 - \frac{kZq^2}{r} = \frac{1}{2} \mu \frac{kZq^2}{\mu r} - \frac{kZq^2}{r} =$$

$$= -\frac{1}{2} \frac{kZq^2}{r} = -\frac{1}{2} \frac{kZq^2}{n^2 h^2} \frac{\mu k Z q^2}{k Z q^2} =$$

$$= -\frac{\mu Z^2 q^4 k^2}{2 h^2} \frac{1}{n^2}$$

$$q=e, Z=1, n=1$$

צדד זה הוא למעשה  $\mu$

$$\mu = \frac{mM}{m+M} = \frac{m}{1+m/M}$$

$$E_1 = -\frac{m}{1+m/M} \frac{e^4 k^2}{2 h^2} = -13.68 eV$$

$$e = 1.6 \cdot 10^{-19} C$$

$$m = 9.1 \cdot 10^{-31} kg$$

$$h = 1.05 \cdot 10^{-34} J \cdot s$$

$$k = 9 \cdot 10^9 \frac{N \cdot m^2}{C^2}$$

$$M = 1.67 \cdot 10^{-27} kg$$

$$\mu = \frac{1}{2} m$$

$$e M = m$$

אנרגיה כוונתית

$$E_1 = -6.85 eV$$