Many-body adiabatic passage: Quantum detours around chaos

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We study the many-body dynamics of stimulated Raman adiabatic passage in the presence of on-site interactions. In the classical mean-field limit, explored in A. Dey *et al.* [Phys. Rev. Lett. **121**, 250405 (2018)], interaction-induced chaos leads to the breakdown of adiabaticity under the quasistatic variation of the parameters, thus producing *low*-sweep-rate boundaries on efficient population transfer. We show that for the corresponding many-body system, alternative quantum pathways from the initial to the target state open up at even slower sweep rates. These quantum detours avoid the chaotic classical path and hence allow a robust and efficient population transfer.

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I. INTRODUCTION

Adiabatic passage is a major tool of quantum control and quantum state engineering. For two-level systems, the Landau-Zener-Stuckelberg-Majorana (LZSM) linear crossing [1–4] has been a prominent paradigm. Three-level configurations offer, in addition to Landau-Zener-like rapid adiabatic passage (RAP) schemes, also the possibility of stimulated Raman adiabatic passage (STIRAP) [5,6], in which an interference-induced dark state allows for the efficient transfer of population from the source to target state without projection onto an intermediate (often spontaneously decaying) state.

A. Nonlinear adiabatic passage

Advances in the field of Bose-Einstein condensation of dilute atomic gases have triggered great interest in generalizations of adiabatic passage scenarios to many-body interacting systems. Interactions were shown to have a dramatic effect on two-mode (Bose-Hubbard dimer) sweep physics, with powerlaw dependence of remanent populations on sweep duration and finite nonadiabatic fractions at slow driving rates beyond a critical interaction strength. Interaction-induced effects were obtained both in the classical nonlinear mean-field limit [7–13] and in semiclassical or quantum many-body treatments [11,14–18]. Similar behavior was obtained for coupled atomic and molecular condensates [19-27]. A common denominator for all these studies is the connection between the nonlinear effect and energetic stability. The unique nonlinear behavior is universally attributed to the emergence of a separatrix, containing a hyperbolic instability.

The effects of interactions on three-mode adiabatic schemes [28–32] are not as well studied as their two-mode counterparts. An attempt to extend the two-mode idea that nonadiabaticity can be determined from energetic stability analysis was made in Ref. [28]. Mean-field adiabatic stationary points (SPs) for nonlinear RAP and STIRAP were found, and the appearance of a so-called horn avoided crossing in the adiabatic energy diagram was consequently linked to the

loss of adiabaticity at low sweep rates. However, as pointed out in [33], the three-mode system offers richer physics than its two-mode counterpart due to its inherent nonintegrability. Specifically, energetic stability of a SP is insufficient to determine its *dynamical* stability because classical trajectories can diverge within a single multidimensional energy surface, containing both chaotic and quasi-integrable domains [34]. Consequently, adiabatic passage efficiency may be affected by the appearance of phase-space structures which are not manifested in the stationary-point energy diagrams. The analysis of adiabatic passage involving such structures goes well beyond the LZSM paradigm or any of its nonlinear extensions.

B. Nonlinear STIRAP through chaos

In Ref. [33], we showed that the loss of adiabaticity during nonlinear STIRAP with repulsive interaction is not related to energetic instability. Instead, adiabaticity breaks down at slow sweep rates due to dynamical instability, which has no trace in the energy bifurcation diagram. This dynamical instability corresponds to the embedding of the followed SP in chaotic strips that emerge within its energy surface. The outcome of this breakdown mechanism is that classical adiabaticity may be restored by *faster* variation of the control parameter to guarantee that the chaotic interval is traversed before ergodization takes place. Thus, in addition to the standard upper sweep-rate boundary required to ensure efficient adiabatic transfer, there exists also a *lower* sweep-rate boundary that ensures successful passage through chaos. This lower boundary increases with the interaction until it coincides with the higher boundary, thus making efficient population transfer impossible beyond a critical interaction strength.

C. Quantum detours around chaos

In this work, we go beyond the classical mean-field picture and study the many-body quantum dynamics of STIRAP in the presence of interparticle interactions. Similar to the quantum two-mode case, classical adiabaticity corresponds to a series of diabatic transitions through avoided crossings between the many-body adiabatic eigenstates. This *classically adiabatic* path is interrupted during chaotic intervals when the followed SP becomes dynamically unstable and the corresponding many-body state loses one-particle coherence. However, due to a diabatic-to-adiabatic transition through a single many-body avoided crossing, quantum detours open up, which avoid the classically chaotic regions in phase space and reenable efficient population transfer from the initial to the target mode.

Outline. The quantum many-body model is presented in Sec. II. Numerical many-body simulations are presented and interpreted in terms of "adiabatic passage through chaos" and "quantum detours" in Sec. III. Conclusions are provided in Sec. IV.

II. THE MANY-BODY MODEL

A. The Bose-Hubbard trimer Hamiltonian

The many-body dynamics of STIRAP in the presence of on-site interaction is modeled by the time-dependent Bose-Hubbard trimer Hamiltonian [28,35-42] for *N* particles in three second-quantized modes that can be either spatial lattice sites or internal atomic states:

$$\mathcal{H} = \mathcal{E}\hat{n}_2 + \frac{U}{2}\sum_{j=1}^3 \hat{n}_i^2 - \frac{1}{2}(\Omega_p(x)\hat{a}_2^{\dagger}\hat{a}_1 + \Omega_s(x)\hat{a}_3^{\dagger}\hat{a}_2 + \text{H.c.}).$$
(1)

Here, \hat{a}_j and \hat{a}_j^{\dagger} are bosonic operators with associated occupations $\hat{n}_j \equiv \hat{a}_j^{\dagger} \hat{a}_j$. The interaction strength is U, while \mathcal{E} is the middle-site bias, equivalent to the one-photon detuning of the optical scheme [5,6]. The couplings are Gaussian Stokes and pump pulses

$$\Omega_{s,p}(x) = K e^{-(x - x_{s,p})^2}, \qquad (2)$$

which depend on the dimensionless parameter *x*. The standard realization is a simple constant-rate sweep $x(t) = t/\tau$, with a "counterintuitive" sequence $x_p - x_s > 0$, as shown in Fig. 1(a).

The dimensionless characteristic parameters of the trimer Hamiltonian of Eq. (1) are the interaction u = UN/K, the couplings $\kappa_{p,s} = \Omega_{p,s}/K$, and the detuning $\varepsilon = \mathcal{E}/K$. We also define an effective interaction parameter,

$$u_{\rm eff}(x) = \frac{UN}{\sqrt{\Omega_p^2(x) + \Omega_s^2(x)}},\tag{3}$$

that reflects the x dependence of the couplings. This quantity is largest in the early and late stages of the process, when the linear coupling terms are small [see Fig. 1(b)].

B. Classical stability and chaos

In the classical limit of the trimer Hamiltonian (see Appendix A) the field operators \hat{a}_j are replaced by *c* numbers $a_j = \sqrt{n_j}e^{i\phi_j}$. The classical motion thus has three degrees of freedom, with $\{n_j, \phi_j\}_{j=1,2,3}$ serving as conjugate actionangle coordinates. Due to conservation of *N*, the classical



FIG. 1. Many-body STIRAP: (a) The STIRAP pulse scheme with the Stokes pulse preceding the pump. Here and below, the classically chaotic intervals and avoided horn crossings are marked by shaded regions and vertical dotted lines, respectively. Here, they are shown for u = 0.2. The detuning here and throughout the paper is $\varepsilon = 0.1$. (b) The effective nonlinearity $u_{\text{eff}}(x)$ for u = 0.1 (dotted blue line), 0.2 (solid black line), and 0.3 (dash-dotted red line). The marked region corresponds to the magnitude of the imaginary part of the characteristic Bogoliubov frequencies around the followed classical SP, i.e., to the region of dynamical instability: The followed SP is embedded in chaos when u_{eff} is inside the shaded region.

phase-space reduces to two freedoms (two population imbalances and two conjugate relative phases). Adiabatic classical motion corresponds to preparing the system near one of the stationary points in this four-dimensional (4D) phase space and following it, as it translates due to the slow variation of x, to the target state. Specifically, in linear STIRAP the followed SP is

$$n_1 - n_3 = N[\cos^2 \vartheta(x) - \sin^2 \vartheta(x)], \phi_1 - \phi_3 = \pi, \quad n_2 = 0,$$
(4)

translating from the first mode to the third mode as the mixing angle $\vartheta(x) \equiv \tan^{-1}[\Omega_p(x)/\Omega_s(x)]$ varies from 0 to $\pi/2$.

Similar adiabatic paths from the initial state to the target state can be found in the presence of moderate interaction [28,33]. The nonlinearity of the classical equations of motion with any given $u \neq 0$ means we should study the *stability* of the followed SP at any value of x during its evolution. This can be done using either Bogoliubov analysis (Appendix B) or numerical simulation (Appendix C). We distinguish between *energetic* stability and *dynamical* stability. The former term applies if the SP is situated at a local minimum or a local maximum of the energy landscape. In Fig. 1(a), energetic stability is lost for the pertinent parameters in between the two vertical dotted lines. These lines correspond to the avoided *horn crossing* of Ref. [28].

By contrast, dynamical instability is indicated by complex Bogoliubov frequencies. In our case, dynamical instability is associated with the embedding of the followed SP in chaotic strips in phase space (Appendix C). The imaginary part of the Bogoliubov frequencies thus corresponds to a rate $1/t_s$, where t_s is a characteristic time for spreading within the chaotic strip. The marked region in Fig. 1(b) images this rate at various interaction strengths. For any given *u*, the chaotic interval during which the SP is embedded in chaos is determined from the *x* range where u_{eff} is inside this dynamical instability region. For example, the shaded interval in Fig. 1(a) corresponds to the duration where the u = 0.2 solid line in Fig. 1(b) enters the unstable region. For any given *u* we denote the width of this chaotic interval as ξ_s .

C. Eigenstates and their purity

Due to total number conservation, the Hilbert space of the quantum many-body system is spanned by the Fock basis states,

$$|n, n_{2}\rangle = \frac{1}{\sqrt{N!}} (\hat{a}_{1}^{\dagger})^{\frac{N-n_{2}+n}{2}} (\hat{a}_{2}^{\dagger})^{n_{2}} (\hat{a}_{3}^{\dagger})^{\frac{N-n_{2}-n}{2}} |\text{vac}\rangle,$$

where $n_2 = 0, 1, ..., N$ is the intermediate site's occupation and $n = n_1 - n_3 = -(N - n_2), ..., N - n_2$ is the population imbalance between the outer sites. Representing the Hamiltonian in this basis, we find the many-body adiabatic eigenstates $|\nu\rangle$ that diagonalize the Hamiltonian at each instant *x*,

$$\mathcal{H}(x)|\nu(x)\rangle = E_{\nu}(x)|\nu(x)\rangle.$$
(5)

(throughout the manuscript, energy is given in units of *K*) The one-particle coherence of any many-body state $|\Psi\rangle$ is quantified by its purity

$$\gamma = \operatorname{Tr}([\rho^{(sp)}]^2), \tag{6}$$

where $\rho_{i,j}^{(sp)} \equiv (1/N) \langle \Psi | \hat{a}_i^{\dagger} \hat{a}_j | \Psi \rangle$ is the reduced single-particle density matrix. The trimer's coherent states are characterized by $\gamma = 1$, whereas completely incoherent states have $\gamma = 1/3$. In Fig. 2(a), we plot the many-body adiabatic energies as a function of *x*, color-coded according to the one-particle coherence of the corresponding eigenstates.

D. The participation number

Given an arbitrary many-body state $|\Psi\rangle$, we can expand it in the many-body adiabatic eigenstate and define

$$p_{\nu} = |\langle \nu | \Psi \rangle|^2. \tag{7}$$

This is essentially the local density of states with respect to the reference Ψ . From this distribution one can extract the *participation number*,

$$PN = \frac{1}{\sum_{\nu} p_{\nu}^2}.$$
 (8)

This quantity corresponds to the number of adiabatic eigenstates that participate in the wave packet $|\Psi\rangle$.

In a strictly adiabatic STIRAP process the time-dependent state $\Psi(t)$ is an instantaneous eigenstate of the $\mathcal{H}(x)$ Hamiltonian at any moment. The time-dependent PN is calculated in the adiabatic basis. Strict adiabaticity means that $PN(t) \approx 1$ at any moment.



FIG. 2. Quantum vs classical spectra. (a) The many-body adiabatic eigenenergies $E_{\nu}(x)$ for an N = 8 particle system with $u = 2\varepsilon = 0.2$. Each line is color-coded according to the one-particle purity γ of the eigenstate. (b) The energies $E_{\rm SP}(x)$ of the classical SPs. In the absence of chaos the SPs can support coherent many-body eigenstates.

III. QUANTUM DYNAMICS

A. Numerical simulations

Consider first the case of linear STIRAP (u = 0). The system is prepared with all particles occupying the first mode, namely, $|\Psi(x = 0)\rangle = |N, 0\rangle$. The adiabatic sweep from x = 0 to $x = x_f$ transfers the population to the third mode [$|\Psi(x = x_f)\rangle \approx |-N, 0\rangle$] by following the coherent dark eigenstate,

$$|\mathrm{SP}\rangle_{x} = \frac{1}{\sqrt{N!}} (\cos\vartheta(x)\hat{a}_{1}^{\dagger} - \sin\vartheta(x)\hat{a}_{3}^{\dagger})^{N} |\mathrm{vac}\rangle.$$
(9)

The dark state (9) does not project on the intermediate mode at any time $(\langle n_2 \rangle_x = 0)$. This state is labeled SP because it corresponds to a semiclassical minimal wave packet, supported by the classical SP whose energy is E[SP] = 0.

As shown in Fig. 2(b), a similar SP (the classical state whose energy is initially E[SP] = u/2) is followed in the case of nonlinear STIRAP with repulsive interaction (u > 0). However, unlike in the linear case, one-particle coherence is not maintained when this point becomes dynamically unstable. Figure 3 shows a close-up of the many-body adiabatic spectrum in the vicinity of the followed classical SP's energy. The one-particle purity along the classical adiabatic path is close to unity, except during the classically chaotic intervals. This is so because when the dynamics becomes chaotic, the phase-space distribution of the many-body eigenstate is spread nearly uniformly throughout the chaotic strip and does not resemble a



FIG. 3. (a) The many-body adiabatic eigenenergies $E_{\nu}(x)$ for N = 30 and u = 0.1. Lines are color-coded as in Fig. 2. Magenta squares indicate the energy of the followed classical SP. (b) The one-particle purity of the many-body adiabatic eigenstates along the classical path (upper blue line) and the participation number of coherent states corresponding to the followed classical SP (lower red line).

localized coherent state. Similarly, if we plot the participation number of a coherent state $|SP\rangle_x$ that corresponds to the followed classical SP [slightly different from Eq. (9) due to the nonlinearity], we see that it increases during the chaotic intervals because this localized state projects equally on all the $|\nu\rangle$ eigenstates that are supported by the chaotic strip. Thus, similar to the classical case, we expect that in order to avoid spreading over these states, the chaotic intervals would have to be traversed fast with respect to the spreading time t_s . In Fig. 4, we plot the results of numerical propagation of the many-body system with the Hamiltonian (1) at different sweep rates. In the first row we plot the mode populations:

$$P_i(t) = \frac{1}{N} \langle \Psi(t) | a_j^{\dagger} a_j | \Psi(t) \rangle, \qquad (10)$$

while in the second and third rows we plot the instantaneous many-body population distribution p_{ν} and the corresponding participation number PN. All quantities are plotted against x(t). Looking at columns Figs. 4(a)-4(c) we see that slower sweep results in *enhanced* spreading of population between many-body eigenstates during the chaotic intervals, accompanied by the corresponding increase in the participation number. However, as shown in Figs. 4(d) and 4(e), further slowing *recovers* efficient transfer and unit participation. This recovery is absent in the classical simulations and is thus a pure quantum many-body effect.

The dependence of STIRAP efficiency $P_3(\infty)$ and the corresponding PN(∞) on the sweep rate \dot{x} is summarized in Fig. 5. We now turn to provide a detailed explanation for the observed \dot{x} dependence. The fastest sweep on the right-hand side of Fig. 5 corresponds to the sudden limit, where no population is transferred and PN \sim 1 simply because the system remains in the initial state. The large participation number hump is the standard sudden to adiabatic transition, with unit participation attained again when there is classical adiabatic passage [see Fig. 4(a)]. However, interesting features emerge at lower sweep rates, where the transfer efficiency *decreases* and the final participation *increases* as the sweep becomes slower. This enhanced spreading at moderately slower sweep rates is equivalent to the semiclassical "passage through chaos"



FIG. 4. Site population dynamics $P_i(t)$ (top), many-body population distribution $p_v(t)$, and the corresponding participation number PN(x) for an N = 30 system with u = 0.1 and $\varepsilon = 0.1$. The plots are against the time-dependent parameter x(t). The sweep rate is (a) $\dot{x}/K = 8.6 \times 10^{-3}$, (b) 6×10^{-3} , (c) 1.2×10^{-3} , (d) 2×10^{-4} , and (e) 6×10^{-6} . Shaded regions and vertical lines mark the chaotic intervals.



FIG. 5. The dependence of STIRAP efficiency on the rate of the sweep: (a) classical, with the predicted boundaries of Eq. (13) marked by vertical dotted and dash-dotted lines, (b) quantum, and (c) PN of the final quantum p_{ν} distribution. Arrows mark the locations of the simulations shown in Figs. 4(a)–4(e). The vertical dashed lines in the inset mark the expected detour thresholds of Eq. (14). The red circle marks the classical adiabatic dynamics of Fig. 9(a), whereas the magenta square and green triangle mark, respectively, the quantum detours of Figs. 9(b) and 9(c).

analysis of Ref. [33]. We review the main results in Sec. III B. By contrast, the quantum recovery at the slowest presented sweep rates [left-hand side of Figs. 5(b) and 5(c); see also Fig. 4(e)] has no classical equivalent [compare the left-hand side of the quantum Fig. 5(b) and the classical Fig. 5(a)]. Its explanation by the emergence of quantum detours around the classically chaotic regions is provided in Sec. III C.

B. Passage through chaos

The Bogoliubov transformation (Appendix B) approximates the Hamiltonian in the vicinity of the SP by a quadratic form, namely,

$$\mathcal{H} = \sum_{j=1}^{d} \omega_j \hat{c}_j^{\dagger} \hat{c}_j, \qquad (11)$$

where *d* is the number of degrees of freedom. For the twofreedom Bose-Hubbard trimer, there are two nonvanishing frequencies $\omega_{1,2}$. Their real part is plotted in Fig. 6 for all *x* throughout the STIRAP evolution at different values of the interaction parameter *u*. The imaginary part of $\omega_{1,2}$ for the same parameters is plotted in Fig. 7. The chaotic interval, within which the SP is dynamically unstable, is identified as the range where the latter is nonzero.



FIG. 6. Real part of the Bogoliubov frequencies for (a) u = 0.1, (b) 0.2, (c) 0.3, (d) -0.1, (e) -0.2, and (f) -0.3. Dotted vertical lines mark the horn crossings (if they exist), where one of the frequencies changes sign, indicating that energetic stability is lost. Dashed vertical lines indicate the borders of the dynamically unstable interval, where the frequencies are complex.

Energetic stability is stricter than *dynamical stability*. It is determined by the signs of $\omega_{1,2}$ when they are real. If both frequencies are positive (negative), the SP is an energy minimum (maximum). Opposite signs indicate a saddle point in the energy landscape, but note again that this does not imply that the followed SP is a hyperbolic point in phase space because the motion *within* a single multidimensional [three-dimensional (3D) in our case] energy surface can still be elliptic $[Im(\omega_j) = 0]$ or hyperbolic $[Im(\omega_j) \neq 0]$.

For repulsive interaction, the followed SP at early and late times where the Hamiltonian is interaction dominated is a



FIG. 7. Imaginary part of the Bogoliubov frequencies for u = 0.1 (dotted magenta lines), 0.2 (dashed red line), 0.3 (solid orange line), and -0.3 (dash-dotted blue line). The imaginary part of $\omega_{1,2}$ when u = -0.1 and u = -0.2 is identically zero (not plotted). The frequencies are complex within an interval of width ξ_s . The instability time t_s is determined by the maximal value of Im(ω). The extraction of these two parameters is illustrated for the u = 0.2 curve.

self-trapped maximum when $u > \varepsilon$ (interaction energy is lost by the transfer of particles from the initial site to either of the unpopulated sites) or an energy saddle point if $0 < u < \varepsilon$ (energy is gained by moving particles to the detuned central site and lost by transfer to the target site). For $0 < u < \varepsilon$ [Fig. 6(a)] the SP remains a saddle at all times. For $u > \varepsilon$ [Figs. 6(b) and 6(c)] we have horn crossing [28], meaning that a local maximum becomes a saddle point. By contrast, for attractive interaction, the SP starts out as a minimum, and the horn crossing, manifested as a minimum to saddle-point transition, exists for any u < 0 [Figs. 6(d)–6(f)].

The dynamical instability appears for $u > \varepsilon/2$ [33] due to the embedding of the followed SP in a chaotic strip (Appendix C). The implication is a lower threshold for the sweep rate required to maintain adiabaticity. If the sweep is too slow, the wave packet has the time to spread over the chaotic strip, coherence is lost, and the terminal transfer efficiency is spoiled. We define a characteristic spreading time as follows:

$$t_s = \frac{\ln 2}{\max[\operatorname{Im}(\omega)]}.$$
 (12)

It is the time that it takes for the dispersion around the SP to double. The chaotic interval's width ξ_s is determined by the condition $\text{Im}(\omega) \neq 0$ (see Fig. 7). The draining of the SP region can be avoided if ξ_s is traversed on a shorter timescale than t_s (see Appendix D). Combining the lower-sweep-rate threshold with the standard upper-sweep-rate adiabaticity threshold, one concludes that adiabatic transfer is feasible within the range

$$\frac{\xi_s}{t_s} < \dot{x} < \frac{1}{3\pi}K.$$
(13)

The upper limit is required for 96% efficiency [6] and ensures a small probability for nonadiabatic transitions in the transverse (energy) direction.

The dependence of the parameters ξ_s and t_s on u was studied in [33]. As the interaction strength increases, the chaotic interval's width grows, while its instability time becomes shorter. Thus, the lower adiabaticity threshold increases monotonically with u. When it becomes larger than the *u*-independent upper threshold, adiabatic passage is no longer possible. These predictions are confirmed by numerical classical simulations, as shown in Fig. 8. The range of effective adiabatic transfer agrees well with the predicted theoretical boundaries. Whereas the upper part of the diagram is just the well-known timescale-separation criterion, the lower chaotic breakdown region has not been previously considered.

C. Quantum detours around chaos

While the appearance of low-sweep-rate boundaries is explained by the semiclassical analysis of Sec. III B, the recovery of STIRAP efficiency at even lower sweep rates in the many-body results of Sec. III A is a pure quantum effect. Its mechanism becomes clear by inspection of the p_{ν} distributions in Fig. 9, which are essentially a close-up of the middle panels of Fig. 4 (note the vertical axis in Fig. 9 is the energy rather than the level index as in Fig. 4). The STIRAP process in Fig. 9(a) [zoom in of Fig. 4(a)] follows the classical SP [i.e., the many-body state traces the classical path in



FIG. 8. Adiabaticity diagram: The shaded blue region corresponds to the range of parameters where the numerically determined transfer efficiency to the target state $P_3(\infty)$ is greater than 96%. Solid lines mark the predicted boundaries of Eq. (13).

Fig. 3(a)] via a series of *diabatic* hops between the many-body states. This correspondence between the classical-adiabatic and the quantum-diabatic paths is also true for the many-body Landau-Zener crossing in the Bose-Hubbard two-mode system [16]. In comparison, the quantum STIRAP recovery shown in Figs. 9(b) and 9(c) [zoom in of Fig. 4(e)] is obtained when the sweep becomes slow enough to make one of these crossings (marked by arrows) adiabatic. The evolution then proceeds diabatically through a series of *nonclassical* states until the symmetrically twin transition is encountered on the exit, and the system returns to the classical path.



FIG. 9. The many-body energy levels $E_{\nu}(x)$ are plotted against x(t) and color-coded according to $p_{\nu}(t)$. (a) and (c) are for the simulations of Figs. 4(a) and 4(e), respectively, whereas (b) is for $\dot{x}/K = 3 \times 10^{-4}$. In (a) the system follows the classically adiabatic path, formed by a sequence of *diabatic* many-body crossings. In (b) and (c), the arrow-marked transitions become adiabatic, leading to two different quantum detours. The rectangles indicate the levels that are supported by the chaotic strip in phase space: their vertical edges mark the chaotic interval as in Fig. 4.



FIG. 10. The many-body number distribution $p_{n,n_2}(t)$ of the followed states in Figs. 9(a) and 9(c). In the classically adiabatic case (top) the many-body state remains coherent, while in the quantum detour case (bottom) it transiently becomes highly nonclassical.

The many-body dynamics thus offers a *quantum detour* that avoids the chaotic potholes. This detour has no classical equivalent. Its nonclassicality is evident when we compare the Fock number distribution $p_{n,n_2} = |\langle n, n_2 | \Psi \rangle|^2$ obtained at different stages of the classical adiabatic path (Fig. 10, top row) and of the quantum detour (Fig. 10, bottom row). The classical distribution corresponds to a coherent state moving from the initial mode to the target mode. By contrast, the number distribution of the quantum detour state is highly nonclassical and projects substantially onto the intermediate state. Thus, unlike classical nonlinear STIRAP in which the intermediate-state population remains negligible [see, e.g., Fig. 4(a)], quantum detours are less robust to spontaneous emission losses from this state.

Returning to Fig. 5, the high-efficiency adiabatic region is classically limited by the boundaries of Eq. (13), as discussed in Sec. III B. The corresponding quantum process exhibits another high-efficiency region below the sweep rate for which the critical many-body crossing becomes adiabatic and the detour opens up. The threshold for opening a quantum detour is thus obtained from the standard linear curve-crossing prescription:

$$\dot{x} < \frac{\Delta_{\nu,\nu'}^2}{\sigma_{\nu,\nu'}}, \quad \sigma_{\nu,\nu'} \equiv \left| \langle \nu | \frac{\partial \mathcal{H}}{\partial x} | \nu' \rangle \right|,$$
 (14)

where $|\nu\rangle$ and $|\nu'\rangle$ are the participating states and $\Delta_{\nu,\nu'}$ is the energy gap at the avoided crossing. This should be contrasted with the one-body ("classical") upper limit of Eq. (13), where the relevant scales are $\Delta \sim \sigma \sim K$. In Fig. 11 we plot the adiabaticity threshold of Eq. (14) for the various avoided crossings, approximating $\sigma_{\nu,\nu'}$ from their slopes. Indeed, the two crossings with the highest thresholds are the ones for which quantum detours are opened in Figs. 9(b) and 9(c). In between the thresholds the PN exhibits an erratic dependence on the sweep rate, which can be regarded as the time-domain version of universal conductance fluctuations. It is due to the interference between the various detour pathways that are available for the evolution.

IV. CONCLUSIONS

The classical dynamics of nonlinear STIRAP is strongly affected by dynamical chaos. For repulsive interaction, it is chaos-induced dynamical instability, rather than energetic



FIG. 11. The adiabaticity threshold $\Delta^2_{\nu,\nu'}/\sigma_{\nu,\nu'}$, with $\sigma_{\nu,\nu'}$ approximated as $\partial \Delta_{\nu,\nu'}/\partial x$, for the avoided crossings between the many-body adiabatic eigenstates. The two crossings with the highest thresholds, marked by circles, are the ones for which a diabatic to adiabatic transition opens up the quantum detours in our numerical simulations.

instability, that causes the nonlinear failure of adiabatic passage and sets low-sweep-rate boundaries for efficient adiabatic transfer. Going beyond the classical picture, the immense increase in state-space dimensionality from the 4D classical phase space to the $\sim N^2/2$ dimensional quantum Hilbert space may open new quantum avenues for adiabatic passage that do not exist in the restricted classical picture. Thus, quantum dynamics offers alternative many-body pathways that circumvent chaos and reenable adiabatic passage in regions where it is classically forbidden. These quantum detours have no classical equivalent and are therefore not based on the classical dark state. They should thus be considered separate many-body adiabatic passage schemes rather than a modification of the classical scenario.

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APPENDIX A: THE SEMICLASSICAL HAMILTONIAN

The mean-field limit of the interacting many-body system is attained as $N \to \infty$ while UN is held fixed. In this limit, the many-body dynamics may be restricted to the $\gamma = 1$ classical coherent states, so that field operators can be replaced by their expectation values $\hat{a}_j \to \langle \hat{a}_j \rangle \equiv a_j = \sqrt{n_j} e^{i\phi_j}$. The classical Hamiltonian therefore takes the form

$$\mathcal{H}_{c1} = \mathcal{E}n_2 - [\Omega_p(x)\sqrt{n_1 n_2} \cos(\phi_2 - \phi_1) - \Omega_s(x)\sqrt{n_2 n_3} \cos(\phi_2 - \phi_3)] + \frac{U}{2} \sum_{j=1}^3 n_j^2.$$
(A1)

Rescaling the classical amplitudes as $a_j \rightarrow a_j/\sqrt{N}$ and time as $t \rightarrow Kt$ and defining $P_j = |a_j|^2$, we obtain the discrete nonlinear Schrödinger equations:

$$i\dot{\mathbf{a}} = (\mathcal{H}_0 + u\mathcal{P})\mathbf{a},$$
 (A2)

where

$$\mathcal{H}_{0} = \begin{pmatrix} 0 & -\kappa_{p}/2 & 0 \\ -\kappa_{p}/2 & \varepsilon & -\kappa_{s}/2 \\ 0 & -\kappa_{s}/2 & 0 \end{pmatrix}, \quad \mathcal{P} = \begin{pmatrix} P_{1} & 0 & 0 \\ 0 & P_{2} & 0 \\ 0 & 0 & P_{3} \end{pmatrix}.$$
(A3)

The classical adiabatic basis consists of the SPs of the grand-canonical Hamiltonian $\mathcal{H}_{cl} - \mu N$, i.e., the classical points that satisfy

$$i\dot{\mathbf{a}} = \mu \mathbf{a},$$
 (A4)

where μ is the chemical potential. The classical adiabatic energies E(SP) are the values of \mathcal{H}_{cl} at these classical SPs. For u = 0, they are just the three well-known eigenenergies of the linear STIRAP scenario [5,6]. The followed SP is the dark state,

$$\boldsymbol{a}_{\rm sp}(x) = (\cos\vartheta(x), 0, -\sin\vartheta(x)), \tag{A5}$$

whose energy is E(SP) = 0. With nonzero interaction, the SPs are shifted and bifurcate if the effective interaction $u_{\text{eff}}(x)$ is sufficiently strong, as seen in Fig. 2(b). One such bifurcation is the horn avoided crossing [28], which appears for $u > \varepsilon$. More SPs, up to a maximum total of eight, emerge as u is increased.

APPENDIX B: BOGOLIUBOV STABILITY ANALYSIS

In order to determine the stability of the followed classical SP \mathbf{a}_{sp} at any x, we employ the Bogoliubov formalism. Linearizing $\mathbf{a} = \mathbf{a}_{sp} + \delta \mathbf{a}$ in Eq. (A2), retaining only linear terms in $\delta \mathbf{a}$, and carrying out the Bogoliubov transformation,

$$\delta \mathbf{a} = e^{-i\mu t} (\mathbf{u} e^{-i\omega t} - \mathbf{v}^* e^{i\omega t}), \tag{B1}$$

we obtain the discrete Bogoliubov equations,

(n)

$$(\mathcal{H}_0 + 2u\mathcal{P}_{\rm sp} - \mu - \omega)\mathbf{u} - u\mathcal{P}_{\rm sp}\mathbf{v} = 0,$$

$$(\mathcal{H}_0 + 2u\mathcal{P}_{\rm sp} - \mu + \omega)\mathbf{v} - u\mathcal{P}_{\rm sp}\mathbf{u} = 0.$$
 (B2)

where \mathcal{P}_{sp} is the occupation matrix \mathcal{P} at $\mathbf{a} = \mathbf{a}_{sp}$. For a system with d degrees of freedom, there are d collective modes $\{\mathbf{u}_i, \mathbf{v}_i\}_{i=1,...,d}$ with corresponding characteristic frequencies ω_i . Our trimer model has, in principle, d = 3 (three n_i, φ_i pairs serving as conjugate action-angle coordinates). However, due to the conservation of the total particle number N, the system is invariant under global phase transformations, leaving only two degrees of freedom (two population imbalances and two relative phases serving as action-angle variables). Accordingly, the Bogoliubov frequencies include a zero mode $\omega_0 = 0$ and two nonvanishing frequencies $\omega_{1,2}$. Defining the quasiparticle operators

$$\hat{c}_i = \mathbf{u}_i \cdot \hat{\mathbf{a}} + \mathbf{v}_i \cdot \hat{\mathbf{a}}^{\dagger} \tag{B3}$$

transforms the many-body Hamiltonian of Eq. (1) in the vicinity of the SP into the approximate quadratic form in Eq. (11).

APPENDIX C: POINCARÉ SECTIONS

The source of dynamical instability is readily seen by plotting quasistatic (frozen-x) Poincaré sections during the STI-RAP sequence. The fixed-energy surfaces within the 4D phase





FIG. 12. Poincaré sections for the frozen Hamiltonian at representative values of x for $u = 2.2\varepsilon = 0.22$. The energy in all panels is E = E(SP) of the followed SP. The cross sections are taken through the $n_2 = n_2$ [SP] plane of the 3D energy surface. We use polar coordinates $z_1 = r \sin \varphi$, $z_2 = r \cos \varphi$, where r = [1 - (n/N)]/2. Magenta dots correspond to a semiclassical cloud, initially localized around the followed SP. Gray shading marks energetically forbidden regions. Note that these panels depict the adiabatic sequence up to the middle point $x \sim 3$. The Poincaré sections at later times mirror the presented panels.

space of the Bose-Hubbard trimer are three-dimensional. For a given N and E our dynamical coordinates are, accordingly, n_2 and n, and the relative phase $\varphi = \varphi_1 - \varphi_3$. The Poincaré section consists of trajectories in the energy surface of the followed SP, E = E[SP]. A trajectory is sampled each time that it intersects the plane $n_2 = n_2$ [SP]. We thus obtain a section whose coordinates are $\mathbf{z} = (\varphi, n)$. These are displayed as polar coordinates in Figs. 12 and 13. The Poincaré section map is thus a Lambert conical projection of a sphere, where the radii are the meridians and the azimuth is the longitude. The origin corresponds to the initial state ($P_1 = 1$) that lies on the north pole, and the z = 1 circumference corresponds to the



FIG. 13. Same as Fig. 12 for attractive interaction: $u = -2.2\varepsilon =$ -0.22



FIG. 14. Same as Fig. 3 for attractive interaction u = -0.1.

target state ($P_3 = 1$) that lies on the south pole. Note that the observed structures do not reflect the topography of the energy landscape but correspond to various periodic orbits, invariant tori, and chaotic regions *on the same energy surface*. The plotted sections contain a single SP that supports the followed adiabatic eigenstate, while the other fixed points are, in fact, periodic orbits. In each section, we plot the distribution obtained by classically evolving a cloud of classical trajectories, initially localized around the followed SP.

The sequence of Poincaré sections in Fig. 12 represents the case of repulsive interaction. At early times (x = 1.1818), the followed SP is an energy maximum near $(n, n_2) = (N, 0)$ (the origin), surrounded by a lower-energy forbidden region (gray). It is degenerate with the other self-trapped maxima near $(n, n_2) = (-N, 0)$ (the circumference) and $(n, n_2) =$ (0, N) (lying outside the $n_2 = n_2[SP]$ section). The followed SP becomes an energy saddle after the horn crossing. Hence, the forbidden region disappears, and an intermediate nonlinear resonance appears as a "belt" in the Poincaré section (x = 2.3939). At larger x, the belt expands, and a chaotic strip is formed along its border (x = 2.6970). The enclosed "island," containing the followed SP, shrinks down until the SP enters the chaotic strip (x = 2.7576). The dynamical instability thus corresponds to the embedding of the followed SP in the chaotic strip, resulting in the quasistochastic spreading of the initially localized distribution over the chaotic region (x = 2.7879). The entire progression takes place on a single 3D energy surface and has no trace in the adiabatic energy diagram.

The situation is quite different for attractive interaction (see Fig. 13). The early-time SP is a minimum since the dominant attractive interaction favors the localization of all particles in one of the three modes. The transition to a saddle point takes place at the horn crossing (present at any u < 0), and a chaotic belt appears here too. However, for $u > -2.2\varepsilon$ the followed SP is located away from the chaotic region at all times and therefore never loses its dynamical stability. Consequently, chaotic intervals do not exist for nonlinear STIRAP with attractive interaction in this range, and the only obstacle to successful adiabatic passage is the traverse of the horn crossing. From the quantum perspective, the absence of a chaotic interval is manifested in the one-particle coherence maintained by the many-body eigenstates



FIG. 15. Close-up of the followed SP region of the Poincaré sections at x = 3.0454 for (a) $u = -2.2\varepsilon$, (b) -3.5ε , and (c) -3.8ε .

along the entire classical path (see Fig. 14 in comparison to Fig. 3). The dynamical instability does reappear for sufficiently strong ($u < -2.2\varepsilon$) attractive interaction [see Fig. 6(f), the dash-dotted line in Fig. 7, and the Poincaré sections in Fig. 15].

APPENDIX D: SEMICLASSICAL STIRAP EFFICIENCY

For repulsive interaction (u > 0), the cause of slow-sweep breakdown of adiabaticity in semiclassical simulations is the dynamical instability (i.e., chaos) rather than energetic instability [33]. For example, In Fig. 16(a), adiabaticity breaks down even if no avoided crossing is present, and the followed SP remains an energy maximum throughout its evolution. Nonadiabatic population oscillations are clearly boosted during the marked chaotic intervals. Moreover, as shown in Fig 16(c), while for $u > \varepsilon$ the horn crossing does appear in an early stage, adiabaticity breaks down even if it is bypassed by initiating the system *after* it.

The situation is entirely different for attractive interaction (u < 0), as illustrated in Fig. 17. Here, the nonlinear break-



FIG. 16. Evolution of the site populations for repulsive interaction. (a) Failure of STIRAP in the absence of SP bifurcations: here, $u = 0.8\varepsilon$ is *below* the critical value for obtaining the horn crossing. The sweep rate is $\dot{x}/K = 6 \times 10^{-5}$. (b) Recovery of the adiabatic passage with *increased* sweep rate ($\dot{x}/K = 6 \times 10^{-4}$) during chaotic intervals. (c) Failure of STIRAP for $u = 2\varepsilon$, with initial conditions that bypass the horn crossing: The process is launched at the adiabatic state *after* the avoided crossing. Sweep rate is $\dot{x}/K = 6 \times 10^{-4}$. (d) For the same *u*, efficiency is recovered due to faster sweep ($\dot{x}/K = 4 \times 10^{-2}$).



FIG. 17. (a) Site population dynamics for attractive interaction, $u = -\varepsilon = -0.1$ and $\dot{x}/K = 6 \times 10^{-6}$. (b) The same as in (a), launching the system after the first horn crossing and stopping before the second. (c) The same as in (a) for $\dot{x}/K = 4 \times 10^{-2}$.

down of adiabaticity takes place immediately at the horn crossing rather than later [see Fig. 17(a)]. Since no chaotic

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intervals are encountered by the followed SP, launching the system after the horn crossing recovers adiabaticity [see Fig. 17(b)], in marked contrast to the repulsive interaction scenario [see Fig. 16(c)]. The cause of failure when the interaction is attractive is thus the inability of the system to *diabatically* traverse the avoided crossing from the prehorn minimum to the posthorn saddle. Here, too, the remedy is a faster sweep, allowing for such diabatic crossing [see Fig. 17(c)].

In principle, a horn-crossing effect exists also for repulsive interaction. However, to see failure due to the horn crossing with u > 0, the sweep rate needs to be well below the threshold for chaotic failure, specified in Eq. (13). Thus, for repulsive interaction, any horn effect is overwhelmed by the passage through the chaos mechanism. The absence of the latter for attractive interaction allows for the observation of the horn-crossing breakdown.

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