

$$\Psi(x, t=0) = \frac{A_0}{2} + \sum_{n=1}^{\infty} A_n \cos k_n x = \begin{cases} \frac{2h}{e}x + 2h, & -l < x < -l/2 \\ -\frac{2h}{e}x, & -l/2 < x < 0 \\ \frac{2h}{e}x, & 0 < x < l/2 \\ -\frac{2h}{e}x + 2h, & l/2 < x < l \end{cases}$$

$$A_n = \frac{1}{l} \int_{-l}^l \Psi(x, t=0) \cos \frac{\pi n}{e} x dx = \quad (n \neq 0)$$

$$= \frac{1}{e} \left(\int_{-l}^{-l/2} \left(\frac{2h}{e}x + 2h \right) \cos \frac{\pi n}{e} x dx + \int_{-l/2}^0 \left(-\frac{2h}{e}x \right) \cos \frac{\pi n}{e} x dx + \right.$$

$$\left. + \int_0^{l/2} \frac{2h}{e}x \cos \frac{\pi n}{e} x dx + \int_{l/2}^l \left(\frac{2h}{e}x + 2h \right) \cos \frac{\pi n}{e} x dx \right) =$$

$$\int x \cos ax dx = \frac{1}{a} x \sin ax - \frac{1}{a} \int \sin ax dx = \frac{1}{a} x \sin ax + \frac{1}{a^2} \cos ax$$

$$= \frac{1}{e} \left(- \int_{e/2}^e \left(-\frac{2h}{e}x' + 2h \right) \cos \frac{\pi n}{e} x' dx' + (-1) \int_{e/2}^0 \frac{2h}{e}x' \cos \frac{\pi n}{e} x' dx' + \right.$$

$$\left. + \int_0^{e/2} \frac{2h}{e}x \cos \frac{\pi n}{e} x dx + \int_{e/2}^l \left(-\frac{2h}{e}x + 2h \right) \cos \frac{\pi n}{e} x dx \right) =$$

$$= \frac{2}{e} \left(\int_0^{e/2} \frac{2h}{e}x \cos \frac{\pi n}{e} x dx + \int_{e/2}^l \left(-\frac{2h}{e}x + 2h \right) \cos \frac{\pi n}{e} x dx \right) =$$

$$= \frac{2}{e} \cdot 2h \left[\frac{1}{e} \left(\frac{e}{\pi n} \left(\frac{e}{2} \sin \frac{\pi n}{e} \frac{e}{2} + \frac{e}{\pi n} \cos \frac{\pi n}{e} \frac{e}{2} - 0 - \frac{e}{\pi n} \cdot 1 \right) - \right.$$

$$\left. - \frac{1}{e} \left(\frac{e}{\pi n} \left(e \sin \frac{\pi n}{e} \cdot e + \frac{e}{\pi n} \cos \frac{\pi n}{e} e - \frac{e}{2} \sin \frac{\pi n}{e} \frac{e}{2} - \frac{e}{\pi n} \cos \frac{\pi n}{e} \frac{e}{2} \right) \right) \right]$$

$$+ \frac{e}{\pi n} \left(\sin \frac{\pi n}{e} \cdot e - \sin \frac{\pi n}{e} \frac{e}{2} \right) \Big] =$$

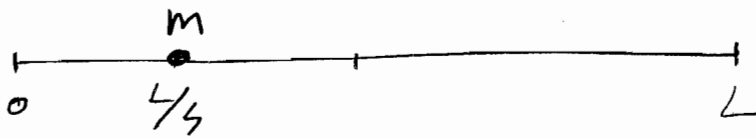
$$= \frac{4h}{\pi n e} \left[\frac{e}{2} (-1)^{n+1} \frac{1}{\pi n} + \frac{e}{\pi n} - \frac{e}{\pi n} (-1)^{n+1} \frac{e}{2} \frac{1}{\pi n} - \frac{e}{\pi n} (-1)^{n+1} \right] =$$

$$= \frac{4h}{\pi n} \left((-1)^{n+1} \frac{1}{\pi n} - \frac{1}{\pi n} \right) = -\frac{4h}{\pi^2 n^2} \left((-1)^n + 1 \right)$$

$$n=0$$

$$A_0 = \frac{1}{e} \int_{-e}^e \psi(x, t=0) dx = h$$

$$\psi(x, t) = \frac{h}{2} - \frac{4h}{\pi^2} \sum_{n=1}^{\infty} \frac{1+(-1)^n}{n^2} \cos\left(\frac{\pi n}{e} x\right) \cos\left(\sqrt{\frac{F}{\rho}} \frac{\pi n}{e} t\right)$$



2 אד"ב

(1) המסה במנוחה.

$$\Psi(x,t) = \cos(\omega t + \varphi) (A \sin kx + B \cos kx)$$

$$\Psi(x=0) = 0 \Rightarrow B = 0$$

$$\Psi(x=L) = 0 \Rightarrow \sin kL = 0 \Rightarrow k_n = \frac{\pi n}{L}$$

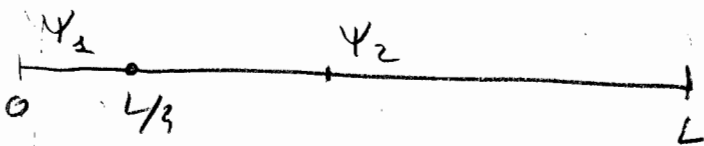
אובני המנוחה נמצאים במסה.

$$\Psi_n(x,t) = A_n \sin \frac{\pi n}{L} x \cos(\omega_n t + \varphi)$$

הנקודה $x = L/5$ (מכיוון המנוחה) שם $\sin\left(\frac{\pi n}{L} \cdot \frac{L}{5}\right) = 0$

שהן נכנסות עקבות $n = 5, 8, 12, \dots$

(2) מש' המסה האופן של:



$$\Psi_1(0) = 0$$

$$\Psi_1(L/5) = \Psi_2(L/5)$$

$$\Psi_2(L) = 0$$

$$T \left(\left. \frac{\partial \Psi_1}{\partial x} \right|_{x=L/5} - \left. \frac{\partial \Psi_2}{\partial x} \right|_{x=L/5} \right) = m \left. \frac{\partial^2 \Psi}{\partial t^2} \right|_{x=L/5}$$

$$\Psi_1 = \cos(\omega t + \varphi_1) (A \sin kx + B \cos kx)$$

$$\Psi_2 = \cos(\omega t + \varphi_2) (C \sin kx + D \cos kx)$$

$$\Psi_2(L) = 0 = C \sin kL + D \cos kL = 0 \Rightarrow D = -C \tan kL \quad (1)$$

$$\Psi_1(L/4) = \Psi_2(L/4)$$

$$\Rightarrow A \sin \frac{kL}{4} = C \sin \frac{kL}{4} - C \tan kL \cos \frac{kL}{4}$$

$$A = C \left(1 - \tan kL \cot \frac{kL}{4} \right) \quad (2)$$

$$T \left(\frac{\partial \Psi_1}{\partial x} \Big|_{L/4} - \frac{\partial \Psi_2}{\partial x} \Big|_{L/4} \right) = m \frac{\partial^2 \Psi}{\partial t^2}$$

$$T \left(A k \cos \frac{kL}{4} - C k \cos \frac{kL}{4} + D k \sin \frac{kL}{4} \right) = -m \omega^2 A \sin \frac{kL}{4} \quad (3)$$

$$(1), (2), (3) \Rightarrow$$

$$k \left(\cos \frac{kL}{4} - \tan kL \cot \frac{kL}{4} \cos \frac{kL}{4} - \cos \frac{kL}{4} \right) - k \tan kL \sin \frac{kL}{4} =$$

$$= - \frac{m \omega^2}{T} \left(\sin \frac{kL}{4} - \tan kL \cos \frac{kL}{4} \right)$$

$$k \tan kL \left(\frac{\cos^2 \frac{kL}{4}}{\sin \frac{kL}{4}} + \sin \frac{kL}{4} \right) = \frac{m \omega^2}{T} \left(\sin \frac{kL}{4} - \tan kL \cos \frac{kL}{4} \right)$$

$$k \tan kL = \frac{m \omega^2}{T} \left(\sin^2 \frac{kL}{4} - \tan kL \cos \frac{kL}{4} \sin \frac{kL}{4} \right)$$

$$\omega = v k$$

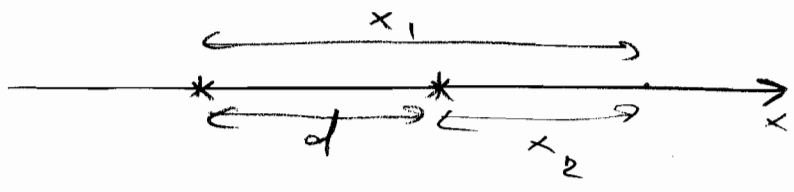
$$\tan kL = \frac{m v^2}{T} k \sin^2 \frac{kL}{4} \left(1 - \tan kL \cot \frac{kL}{4} \right)$$

התנאי של קוטר (למשל)

$$\begin{aligned}
 a \cos \alpha + b \cos \beta &= \\
 &= \frac{1}{2}(a+b)(\cos \alpha + \cos \beta) + \frac{1}{2}(a-b)(\cos \alpha - \cos \beta) = \\
 &= (a+b) \cos \frac{1}{2}(\alpha + \beta) \cos \frac{1}{2}(\alpha - \beta) - (a-b) \sin \frac{1}{2}(\alpha + \beta) \sin \frac{1}{2}(\alpha - \beta)
 \end{aligned}$$

$$\Psi(r, t) = A(r) \cos(\omega t - kr)$$

כאן r הוא המרחק $\int dx$
 אורך הגל $\lambda = \frac{2\pi}{k}$ $A(r)$ (1)

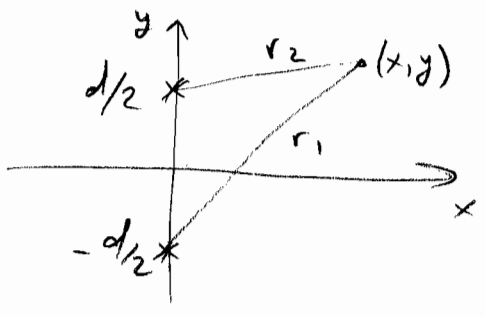


$$d = x_2 - x_1$$

$$\begin{aligned}
 \Psi_1 + \Psi_2 &= A(x_1) \cos(\omega t - kx_1) + A(x_2) \cos(\omega t - kx_2) = \\
 &= (A(x_1) + A(x_2)) \cos(\omega t - k \frac{x_1 + x_2}{2}) \cos(\frac{k(x_2 - x_1)}{2}) - \\
 &\quad - (A(x_1) - A(x_2)) \sin(\omega t - k \frac{x_1 + x_2}{2}) \sin(\frac{k(x_2 - x_1)}{2})
 \end{aligned}$$

$$\begin{aligned}
 I &= \langle (\Psi_1 + \Psi_2)^2 \rangle = \frac{1}{2} (A(x_1) + A(x_2))^2 \cos^2 \frac{k d}{2} + \\
 &\quad + \frac{1}{2} (A(x_1) - A(x_2))^2 \sin^2 \frac{k d}{2} = \\
 &= \frac{1}{2} [A^2(x_1) + A^2(x_2) + 2A(x_1)A(x_2) \cos kd]
 \end{aligned}$$

התנאי של קוטר (למשל)



$$\begin{aligned}
 r_1^2 &= x^2 + (y + \frac{d}{2})^2 \\
 r_2^2 &= x^2 + (y - \frac{d}{2})^2
 \end{aligned}$$

$$r_1, r_2 \gg d$$

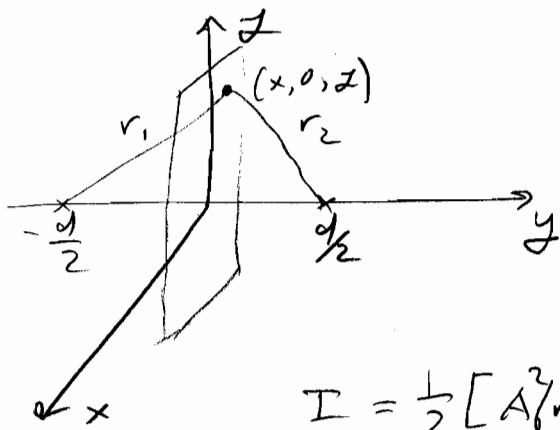
$$R = \frac{r_1 + r_2}{2}$$

$$\begin{aligned}
 r_1^2 - r_2^2 &= (y + \frac{d}{2})^2 - (y - \frac{d}{2})^2 = 2yd = (r_1 - r_2)(r_1 + r_2) = \\
 &= 2R(r_1 - r_2)
 \end{aligned}$$

$$I \approx \frac{1}{2} [A^2(r_1) + A^2(r_2) + 2A(r_1)A(r_2) \cos(k \frac{y}{R} d)]$$

$$\cos(k \frac{y}{R} d) = -1 \quad \frac{y}{R} = \frac{(2n+1)\pi}{kd}$$

התנאי של קוטר (למשל)



$$r_1^2 = x^2 + \left(\frac{d}{2}\right)^2$$

$$r_2^2 = x^2 + \left(\frac{d}{2}\right)^2$$

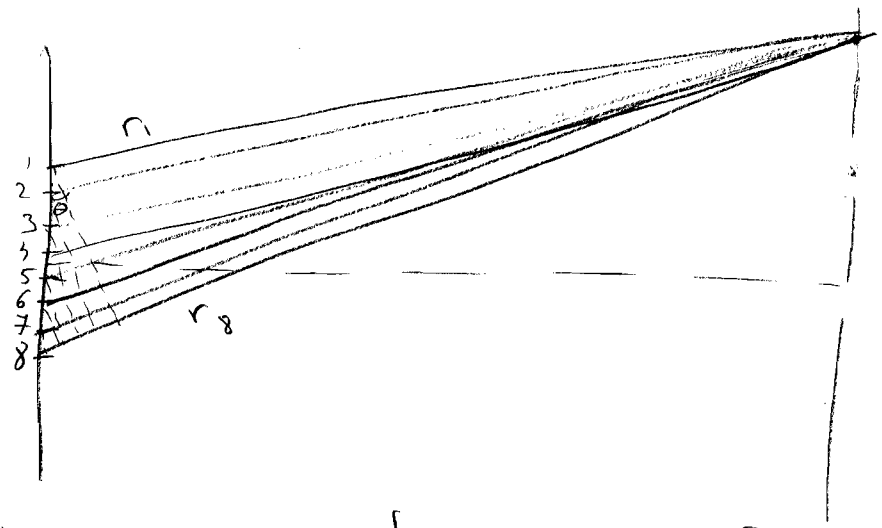
(d)

$$r_1 - r_2 = 0$$

$$I = \frac{1}{2} [A^2(r_1) + A^2(r_2) + 2A(r_1)A(r_2) \cdot 1] =$$

$$= \frac{1}{2} (A(r_1) + A(r_2))^2$$

השדה יוצא עם המרחק.



(10)

כיוון שהמסך כחוק הצוויר ה'ן δ קבן לישב המ'ל אר הקוקות שלה
 הפס הקכ'ים האוליות ה'ן δ שר' קבן'ים סמוכר $\Delta = d \sin \theta$
 והפס הקכ'ים א'ים δ קבן הכאל'ה הוא $\Delta_n = (n-1)d \sin \theta$
 אשכ n- מסכ הקוק'י
 מס' הקוק' n ו'ל א' d
 $\psi_n = A e^{i(\omega t - kr_n + \varphi_n)}$
 $\varphi_1 = \varphi_3 = \varphi_5 = \varphi_7 = 0$
 $\varphi_2 = \varphi_4 = \varphi_6 = \varphi_8 = \delta$
 $r_n = r_1 + \Delta_n = r_1 + (n-1)d \sin \theta$

$$\Psi = \sum_{n=1}^8 \Psi_n = A e^{i\omega t} e^{-ikr_1} \left(1 + e^{i\delta} + e^{i2\delta} + e^{i3\delta} + e^{i4\delta} + e^{i5\delta} + e^{i6\delta} + e^{i7\delta} \right)$$

$$= A e^{i(\omega t - kr_1)} \left(\frac{e^{-i\delta} - 1}{e^{-i\delta} - 1} + e^{i\delta} \frac{e^{-i\delta} - 1}{e^{-i\delta} - 1} + e^{i2\delta} \frac{e^{-i\delta} - 1}{e^{-i\delta} - 1} + e^{i3\delta} \frac{e^{-i\delta} - 1}{e^{-i\delta} - 1} + e^{i4\delta} \frac{e^{-i\delta} - 1}{e^{-i\delta} - 1} + e^{i5\delta} \frac{e^{-i\delta} - 1}{e^{-i\delta} - 1} + e^{i6\delta} \frac{e^{-i\delta} - 1}{e^{-i\delta} - 1} + e^{i7\delta} \frac{e^{-i\delta} - 1}{e^{-i\delta} - 1} \right)$$

$$= A e^{i(\omega t - kr_1)} \frac{e^{-i4\delta} (e^{-i4\delta} - e^{i4\delta})}{e^{-i\delta} (e^{-i\delta} - e^{i\delta})} \left(1 + e^{i(\delta - \delta)} \right) =$$

$$= A e^{i(\omega t - kr_1)} e^{-i3\delta} \frac{\sin 4\delta}{\sin \delta} e^{\frac{1}{2}i(\delta - \delta)} 2 \cos\left(\frac{1}{2}(\delta - \delta)\right)$$

$$\text{Re } \Psi = 2A \cos(\omega t - kr_1 - 3\delta + \frac{1}{2}\delta - \frac{1}{2}\delta) \frac{\sin 4\delta}{\sin \delta} \cos\left(\frac{1}{2}(\delta - \delta)\right)$$

$$I = I_0 \frac{\sin^2 4\delta}{\sin^2 \delta} \cos^2\left(\frac{1}{2}(\delta - \delta)\right) \quad \Delta = d \sin \theta$$

$$\delta = \pi$$

$$I = I_0 \frac{\sin^2 4\delta}{\sin^2 \delta} \sin^2 \frac{1}{2}\delta = \frac{1}{3} I_0 \frac{\sin^2 4\delta}{\cos^2 \frac{1}{2}\delta} = I_0 \left(\frac{\sin 4\delta}{2 \cos \frac{1}{2}\delta} \right)^2 \quad (2)$$

Bohr quantization

$$L = n\hbar$$

$$L = mvr = n\hbar$$

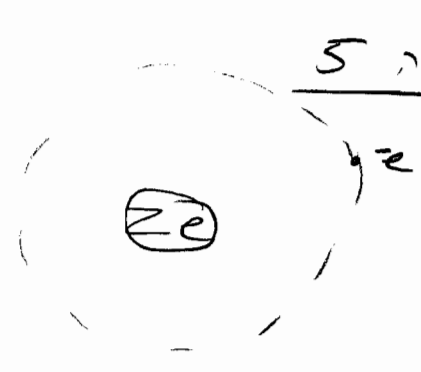
$$K \frac{Ze^2}{r^2} = m \frac{v^2}{r}$$

$$v^2 = \frac{kZe^2}{mr} = \frac{kZe^2}{m \frac{n\hbar}{mv}} = \frac{kZe^2}{n\hbar} v$$

$$v_1 = \frac{kZe^2}{n\hbar}$$

$$r_n = \frac{n\hbar}{mv} = \frac{n^2 \hbar^2}{m k Z e^2}$$

$$E_n = \frac{1}{2} m v^2 - \frac{kZe^2}{r} = \frac{1}{2} m \left(\frac{k^2 Z^2 e^4}{n^2 \hbar^2} \right) - \frac{kZe^2 \cdot m k Z e^2}{n^2 \hbar^2} = -\frac{m k^2 Z^2 e^4}{2 n^2 \hbar^2}$$



de Broglie

$$2\pi r = n\lambda \quad \lambda = \frac{h}{p} = \frac{2\pi\hbar}{p} \Rightarrow r = \frac{n\hbar}{mv}$$

$$L = mvr = n\hbar \rightarrow \text{Bohr}$$

$$E_n = -\frac{Z^2 \cdot E_1^{(0)}}{n^2} \quad E_1^{(0)} = 13.6 \text{ eV}$$

$$\lambda = \frac{h}{p} = \frac{hc}{E} = \frac{hc}{E_n - E_m} = \frac{hc}{Z^2 E_1^{(0)} \left(\frac{1}{n^2} - \frac{1}{m^2} \right)}$$

$$-\frac{1}{n^2} + \frac{1}{m^2} = \frac{hc}{Z^2 E_1^{(0)} \lambda} \quad \lambda \approx 400 \text{ nm} < \lambda < 700 \text{ nm}$$

$$0.03 \lesssim \frac{1}{m^2} - \frac{1}{n^2} \lesssim 0.06 \quad Z=2$$

The allowed transitions are $4 \rightarrow 3, n \rightarrow 4 (n > 3)$
(for $Z=2$)